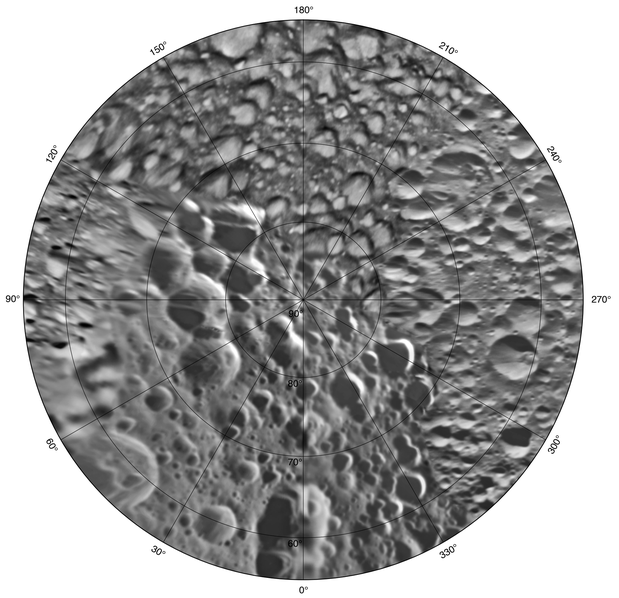
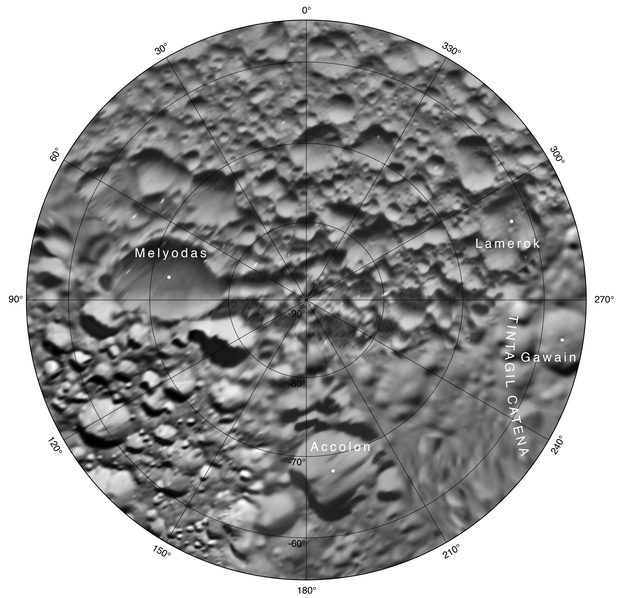



NORTH POLAR REGION




SOUTH POLAR REGION

Scale 1:1 000 000

0 20 40 60 km

## GENERAL NOTES

This map sheet is the 1st of a 3-quadrangle series covering the entire surface of Mimas at a nominal scale of 1: 1 000 000. This 3-quadrangle series is the third version of the Mimas atlas and supersedes the release from 2010[1]. The source of map data was the Cassini imaging experiment (Porco et al., 2004)[2]. Cassini-Huygens is a joint NASA/ESA/ASI mission to explore the Saturnian system. The Cassini spacecraft is the first spacecraft studying the Saturnian system of rings and moons from orbit; it entered Saturnian orbit on July 1st, 2004.

The Cassini orbiter has 12 instruments. One of them is the Cassini Imaging Science Subsystem (ISS), consisting of two framing cameras. The narrow angle camera is a reflecting telescope with a focal length of 2000 mm and a field of view of 0.35 degrees. The wide angle camera is a refractor with a focal length of 200 mm and a field of view of 3.5 degrees. Each camera is equipped with a large number of spectral filters which, taken together, span the electromagnetic spectrum from 0.2 to 1.1 micrometers. At the heart of each camera is a charged coupled device (CCD) detector consisting of a 1024 square array of pixels, each 12 microns on a side.

## MAP SHEET DESIGNATION

| | |
|---|---|
| Sm | Mimas (Saturnian satellite) |
| 1M | Scale 1 : 1 000 000 |
| +/-90/0 | Center point in degrees consisting of latitude/west longitude |
| SMN | Semi-controlled Mosaic with Nomenclature |
| 2017 | Year of publication |

## IMAGE PROCESSING [3]

- Radiometric correction
- Geometric correction
- Photogrammetric adjustment using limb-fitting techniques
- Map projection
- Photometric correction using the Hapke bidirectional reflectance function
- Processing of the mosaic

## CONTROL

For the Cassini mission, spacecraft position and camera pointing data are available in the form of SPICE kernels. SPICE is a data system providing ancillary data such as spacecraft and target positions, target body size/shape/orientation, spacecraft-orientation, instrument pointing used for planning space science missions and recovering the full value of science instrument data returned from missions (http://naif.jpl.nasa.gov/). While the orbit information was sufficiently accurate to be used directly for mapping purposes, the pointing information was improved using limb-fit techniques. Newly derived tri-axial ellipsoid models were used to calculate the surface intersection points. A spherical reference surface is used for map projections.

The longitude system by Davies and Katayama (1983)[4] and adopted by the IAU/IAG (International Astronomical Union/International Association of Geodesy) Working Group on Cartographic Coordinates and Rotational Elements as standard (Archinal et al., 2011)[5] is defined by crater Palomides; this crater defines the 162° W meridian.

## MAP PROJECTION

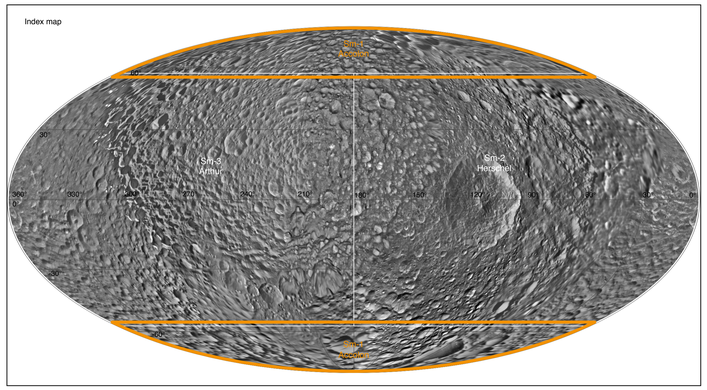
Polar Stereographic projection
Scale is true at +/-90°
Adopted figure: sphere
Mean radius: 198.2 km [6]

Grid system: planetographic latitude, west longitude

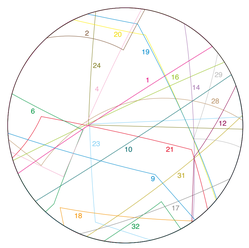
## NOMENCLATURE

Names are approved by the International Astronomical Union (IAU). For a detailed list of IAU-approved names on Mimas, see the Gazetteer of Planetary Nomenclature at http://planetarynames.wr.usgs.gov/.

Index map




Index of Cassini images

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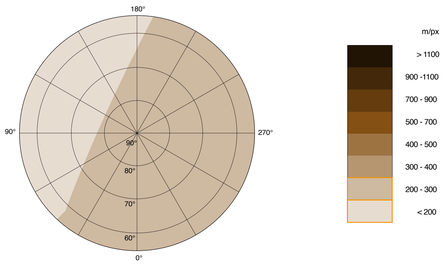
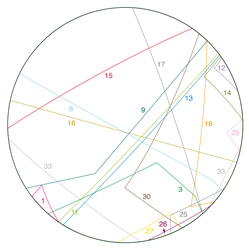
NORTH POLAR REGION

Resolution of the images




NORTH POLAR REGION

Index of Cassini images

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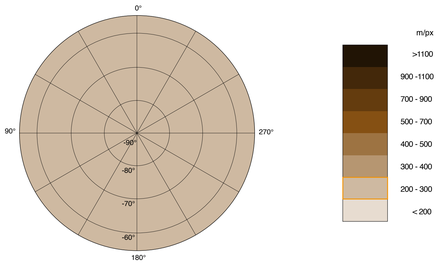
SOUTH POLAR REGION

Resolution of the images




SOUTH POLAR REGION

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[1] Roatsch, Th., Kersten, E., Hoffmeister, A., Wählisch, M., Matz, K.-D., Porco, C.C., 2013, Recent improvements of the Saturnian satellites atlases: Mimas, Enceladus, and Dione, Planetary and Space Science 77, 118-125.

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Image processing: Kersten, E., Roatsch, Th., Scholten, F., Matz, K.-D.
Cartographic production and design: Kersten, E., Wählisch, M.

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